

SimTraffic Calibration Settings

Last Updated: 11-27-2017

Type of Setting	Parameter Grouping	Parameter Name	Default Settings (per SimTraffic v. 10.1.1.1)	Recommended Parameter Value	Typical Parameters Adjusted During Calibration	Parameter Description
GLOBAL SETTINGS (Adjusted within SimTraffic)	Driver Parameters	Yellow Deceleration (ft/s ²)	7.0 - 12.0	8 to 10	Yes	Increase to make drivers less prone to running red lights.
		Speed Factor (%)	0.85 - 1.15	No range specified	Yes	Can be changed to increase or decrease the range of driver speeds (e.g. for a link speed of 50 mph and a speed factor of 1.1, the driver will attempt to maintain a speed of 55 mph).
		Courtesy Deceleration (ft/s ²)	3.0 - 10.0	7 to 9	Yes	Amount of deceleration a vehicle will accept in order to allow a vehicle ahead to make a mandatory lane change. Higher value = more courteous driver.
		Yellow Reaction Time (s)	0.7 - 1.7	No range specified	No	Amount of time it takes a driver to respond to a signal changing to yellow. More aggressive drivers will have a longer reaction time to yellow lights. Longer reaction times tends to reduce red light running for higher speed approaches and vehicles slowing to make a turn, however, may increase red light running for low speed approaches.
		Green Reaction Time (s)	0.2 - 0.8	0.5 to 2.0	Yes	Amount of time it takes the driver to respond to a signal changing green. More aggressive drivers will have a shorter reaction time to green lights.
		Headway at 0 mph (s)	0.35 - 0.65	No range specified	Yes, typically modify last	Interpolation used between these factors. May be necessary to change to match local driver parameters. The default headways provide an Saturation Flow Rate similar to the HCM (1900 vphpl) from 25 to 50 mph.
		Headway at 20 mph (s)	0.80 - 1.80	2 to 2.5		
		Headway at 50 mph (s)	1.00 - 2.20	1.7 to 2.0		
		Headway at 80 mph (s)	1.00 - 2.20	2.0 to 2.5		
		Gap Acceptance Factor	0.85 - 1.15	No range specified	Yes	Gap vehicles will accept at unsignalized intersections, for permitted left-turns, and for right turns on red. Higher values represent more conservative drivers.
		Positioning Advantage (veh)	1.2 - 15.0	Use defaults	No	Drivers will make a positioning lane change when there is $\geq x$ vehicles ahead in the target lane than in the current lane. Higher values are associated with more conservative drivers and cause drivers to line up in correct lane. Low values are associated with aggressive drivers and cause drivers to avoid lining up in the correct lane until reaching the mandatory lane change point.
		Optional Advantage (veh)	0.5 - 2.3	Use defaults	No	Drivers will make a desired lane change when $\leq x$ vehicles are ahead in the target lane than in the current lane. Higher values are associated with more conservative drivers and cause drivers to have unbalanced lane use. Lower values are associated with aggressive drivers and cause drivers to use lanes evenly.
		Mandatory Distance Adjustment (%)	50 - 200	No range specified	Yes	Global multiplier for local lane change settings.
		Positioning Distance Adjustment (%)	60 - 150	No range specified	Yes	Global multiplier for local lane change settings.
	Average Lane Change Time (s)	10 - 55	No range specified	No	Average time between lane change maneuvers. Applies only to optional lane changes, which are made to choose a lane with less congestion. Less time applies to more aggressive drivers.	
Lane Change Variance +/- (%)	10 - 30	No range specified	No	Adjustment similar to Average Lane Change Time, but base on driver type. Applies only to optional lane changes, which are made to choose a lane with less congestion. Higher percentage leads to increased awareness of lane change.		
Vehicle Parameters	Vehicle parameters (Occurrence, acceleration, dimensions, etc.)	See Synchro Studio 10 User Guide, Chapter 26 (page 26-7)	Defaults typically acceptable Modify vehicle fleet based on field classification counts if needed	Yes	Modify vehicle percentages based on nearest classification count. Fleet mix should add up to 100% for all truck types and 100% for all car types.	

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LOCAL SETTINGS (Adjusted within Synchro)	Synchro Settings	Link Speed (Lane Settings)	30	Start with posted. Adjust to reflect free flow speed (typically posted + 5 mph), if needed.	Yes	May be adjusted to match field speeds if data is available and speeds are not being used for validation
		Ideal Saturation Flow Rate (Lane Settings)	1,900	Adjust to match field if field data is available	Yes	Refer to TEOpS 16-15-5 for additional guidance on saturation flow rates for through lanes
		Growth Factor (Volume Settings)	1.0	Use for sensitivity testing or future year scenarios. Do not use for RTOR	No	
		Headway Factor (Simulation Settings)	1.0	0.8 to 1.2	Yes	Can be set on a per-movement basis. Can be used to calibrate the Saturated Flow Rates.
		Turning Speed (Simulation Settings)	9 mph (right-turns) 15 mph (left-turns)	Right turns = 12 to 15 mph	Yes	Default speeds are set for small radius urban intersections. With large suburban intersections, turning speeds may be significantly higher. Right-turns speeds need to be adjusted to or near the freeway speeds when simulating entrance ramps. At low speeds, the Saturated Flow Rate is highly sensitive to small changes in speed. Right-turns: SimTraffic = 9 mph (1545 vph). HCM for protected rights = 1615 vphpl Left-turns: SimTraffic = 15 mph (1883 vph). HCM for protected left-turns = 1805 vph.
		Mandatory Distance (Simulation Settings)	333	Base on field conditions	Yes	Distance ahead vehicle is forced to make lane change. Measured from Stop bar. Increase to allow vehicles to shift into correct lane earlier. Decrease to allow vehicles to shift into lane at the last possible moment. Large cities: Shorter mandatory distances Small towns: Longer mandatory distances. Useful to adjust with congested signals or lane drops after signals. With long turn bays consider setting this to less than the storage distance to allow for some late lane changes.
		Positioning Distance (Simulation Settings)	1320	Base on field conditions	Yes	Distance ahead vehicle starts to attempt lane change. Measured from Stop bar.
		Mandatory Distance2 (Simulation Settings)	880	Base on field conditions	Yes	Additional mandatory distance to make 2 lane changes. Measured from Stop bar. Typically used more for high-speed facilities. See Synchro Studio 10 User Guide, Chapter 28 (pages 28-5 to 28-18)
		Positioning Distance2 (Simulation Settings)	1760	Base on field conditions	Yes	Additional positioning distance to make 2 lane changes. Measured from Stop bar. Typically used more for high-speed facilities. See Synchro Studio 10 User Guide, Chapter 28 (pages 28-5 to 28-18)
		Lane Alignment (Simulation Settings)	Right for right-turns Left for left-turns and thru movements Right-NA for U-turns	Base on field conditions	Yes	
		Enter Blocked Intersection (Simulation Settings)	"No" for intersections	Code 1 vehicle if used Yes for driveways No for high speed movements	Yes	Enter "No" for high speed approaches and movements. "Yes" can help capacity of driveways. In general, controls gridlock avoidance.
		Taper Length (Simulation Settings)	25	Code as part of storage based on field conditions	Yes	Impacts when vehicles can start entering the storage.